# **Today**

Estimation.

MMSE: Best Function that predicts X from Y.

Conditional Expectation.

Finish Linear Regression:

Best linear function prediction of *Y* given *X*.

Applications to random processes.

### Review

**Definitions** Let X and Y be RVs on  $\Omega$ .

- ▶ Joint Distribution: Pr[X = x, Y = y]
- ▶ Marginal Distribution:  $Pr[X = x] = \sum_{v} Pr[X = x, Y = y]$
- ► Conditional Distribution:  $Pr[Y = y | X = x] = \frac{Pr[X = x, Y = y]}{Pr[X = x]}$

## Estimation: Expectation and Mean Squared Error.

"Best" guess about *Y*, is *E*[*Y*].

If "best" is Mean Squared Error.

More precisely, the value of a that minimizes  $E[(Y-a)^2]$  is a=E[Y].

#### Proof:

Let  $\hat{Y} := Y - E[Y]$ .

Then, 
$$E[\hat{Y}] = E[Y - E[Y]] = E[Y] - E[Y] = 0$$
.  
So,  $E[\hat{Y}c] = 0, \forall c$ . Now,
$$E[(Y - a)^2] = E[(Y - E[Y] + E[Y] - a)^2]$$

$$= E[(\hat{Y} + c)^2] \text{ with } c = E[Y] - a$$

$$= E[\hat{Y}^2 + 2\hat{Y}c + c^2] = E[\hat{Y}^2] + 2E[\hat{Y}c] + c^2$$

$$= E[\hat{Y}^2] + 0 + c^2 \ge E[\hat{Y}^2].$$

Hence,  $E[(Y - a)^2] \ge E[(Y - E[Y])^2], \forall a$ .

# **Conditional Expectation**

**Definition** Let X and Y be RVs on  $\Omega$ . The conditional expectation of Y given X is defined as

$$E[Y|X] = g(X)$$

where

 $g(x) := E[Y|X = x] := \sum_{y} y Pr[Y = y|X = x].$ 

Fact  $E[Y|X=x] = \sum_{\omega} Y(\omega) Pr[\omega|X=x].$ 

**Proof:** E[Y|X=x] = E[Y|A] with  $A = \{\omega : X(\omega) = x\}$ .

### Estimation: Preamble

Thus, if we want to guess the value of Y, we choose E[Y]. Now assume we make some observation X related to Y. How do we use that observation to improve our guess about Y?

# Properties of CE

$$E[Y|X=x] = \sum_{y} yPr[Y=y|X=x]$$

#### Theorem

- (a) X, Y independent  $\Rightarrow E[Y|X] = E[Y]$ ;
- (b) E[aY + bZ|X] = aE[Y|X] + bE[Z|X];
- (c)  $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot);$
- (d)  $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot);$
- (e) E[E[Y|X]] = E[Y].

#### Proof:

(a),(b) Obvious

(c) 
$$E[Yh(X)|X=x] = \sum_{\omega} Y(\omega)h(X(\omega))Pr[\omega|X=x]$$
  
 $= \sum_{\omega} Y(\omega)h(x)Pr[\omega|X=x] = h(x)E[Y|X=x]$ 

## Properties of CE

$$E[Y|X=x] = \sum_{v} yPr[Y=y|X=x]$$

### Theorem

- (a) X, Y independent  $\Rightarrow E[Y|X] = E[Y]$ ;
- (b) E[aY + bZ|X] = aE[Y|X] + bE[Z|X];
- (c)  $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot);$
- (d)  $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot);$
- (e) E[E[Y|X]] = E[Y].

### Proof: (continued)

(d) 
$$E[h(X)E[Y|X]] = \sum_{x} h(x)E[Y|X=x]Pr[X=x]$$
$$= \sum_{x} h(x)\sum_{y} yPr[Y=y|X=x]Pr[X=x]$$
$$= \sum_{x} h(x)\sum_{y} yPr[X=x,y=y]$$
$$= \sum_{x,y} h(x)yPr[X=x,y=y] = E[h(X)Y].$$

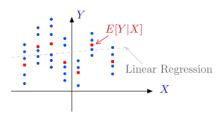
# CE = MMSE (Minimum Mean Squared Estimator)

#### Theorem

E[Y|X] is the 'best' guess about Y based on X.

Specifically, it is the function g(X) of X that

minimizes 
$$E[(Y-g(X))^2]$$
.



## Properties of CE

$$E[Y|X=x] = \sum_{Y} yPr[Y=y|X=x]$$

#### Theorem

- (a) X, Y independent  $\Rightarrow E[Y|X] = E[Y]$ ;
- (b) E[aY + bZ|X] = aE[Y|X] + bE[Z|X];
- (c)  $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot);$
- (d)  $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot);$
- (e) E[E[Y|X]] = E[Y].

Proof: (continued)

(e) Let h(X) = 1 in (d).

## CE = MMSE

#### Theorem CE = MMSE

g(X) := E[Y|X] is the function of X that minimizes  $E[(Y-g(X))^2]$ . **Proof:** Recall: Expectation of r.v. minimizes mean squared error.

Sample space X = x: so E[Y|X = x] minimizes mean squared error.

#### Proof:

Let h(X) be any function of X. Then

$$E[(Y - h(X))^{2}] = E[(Y - g(X) + g(X) - h(X))^{2}]$$

$$= E[(Y - g(X))^{2}] + E[(g(X) - h(X))^{2}]$$

$$+2E[(Y - g(X))(g(X) - h(X))].$$

But,

$$E[(Y-g(X))(g(X)-h(X))]=0$$
 by the projection property.

Thus, 
$$E[(Y - h(X))^2] \ge E[(Y - g(X))^2]$$
.

## Properties of CE

#### Theorem

 $\Box$ .

- (a) X, Y independent  $\Rightarrow E[Y|X] = E[Y]$ ;
- (b) E[aY + bZ|X] = aE[Y|X] + bE[Z|X];
- (c)  $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot);$
- (d)  $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot);$
- (e) E[E[Y|X]] = E[Y].

Note that (d) says that

$$E[(Y - E[Y|X])h(X)|X] = 0.$$

Note: one view is that the estimation error Y - E[Y|X] is orthogonal to every function h(X) of X.

This the projection property. Won't discuss projection property in this offering.

# Application: Going Viral

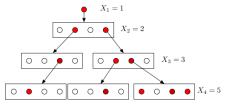
Consider a social network (e.g., Twitter).

You start a rumor (e.g., Rao is not funny.)

You have d friends. Each of your friend retweets w.p. p.

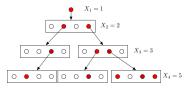
Each of your friends has d friends, etc.

Does the rumor spread? Does it die out (mercifully)?



In this example, d = 4.

### Application: Going Viral



**Fact:** Number of tweets  $X = \sum_{n=1}^{\infty} X_n$  where  $X_n$  is tweets in level n. Then,  $E[X] < \infty$  iff pd < 1.

### Proof:

Given  $X_n = k$ ,  $X_{n+1} = B(kd, p)$ . Hence,  $E[X_{n+1} | X_n = k] = kpd$ .

Thus,  $E[X_{n+1}|X_n] = pdX_n$ . Consequently,  $E[X_n] = (pd)^{n-1}, n \ge 1$ .

If pd < 1, then  $E[X_1 + \cdots + X_p] \le (1 - pd)^{-1} \Longrightarrow E[X] \le (1 - pd)^{-1}$ .

If pd > 1, then for all C one can find n s.t.

$$E[X] \geq E[X_1 + \cdots + X_n] \geq C.$$

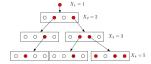
In fact, one can show that  $pd \ge 1 \implies Pr[X = \infty] > 0$ .

## Summary

#### Conditional Expectation

- ▶ Definition:  $E[Y|X] := \sum_{v} yPr[Y = y|X = x]$
- ▶ Properties: E[Y E[Y|X]h(X)|X] = 0; E[E[Y|X]] = E[Y]
- Applications:
  - Viral Propagation.
  - Wal
- ▶ MMSE: E[Y|X] minimizes  $E[(Y-g(X))^2]$  over all  $g(\cdot)$

## Application: Going Viral



An easy extension: Assume that everyone has an independent number  $D_i$  of friends with  $E[D_i] = d$ . Then, the same fact holds.

To see this, note that given  $X_n = k$ , and given the numbers of friends  $D_1 = d_1, \dots, D_k = d_k$  of these  $X_n$  people, one has  $X_{n+1} = B(d_1 + \dots + d_k, p)$ . Hence,

$$E[X_{n+1}|X_n=k,D_1=d_1,\ldots,D_k=d_k]=p(d_1+\cdots+d_k).$$

Thus,  $E[X_{n+1}|X_n = k, D_1, \dots, D_k] = p(D_1 + \dots + D_k).$ 

Consequently,  $E[X_{n+1}|X_n=k]=E[p(D_1+\cdots+D_k)]=pdk$ .

Finally,  $E[X_{n+1}|X_n] = pdX_n$ , and  $E[X_{n+1}] = pdE[X_n]$ .

We conclude as before.

### Linear Estimation: Preamble

Thus, if we want to guess the value of Y, we choose E[Y].

Now assume we make some observation *X* related to *Y*.

How do we use that observation to improve our guess about *Y*?

The idea is to use a function g(X) of the observation to estimate Y.

The "right" function is E[X|Y].

A simpler function?

"Simplest" function is linear: g(X) = a + bX.

What is the best linear function? That is our next topic.

## Application: Wald's Identity

Here is an extension of an identity we used in the last slide.

**Theorem** Wald's Identity

Assume that  $X_1, X_2, ...$  and Z are independent, where

Z takes values in  $\{0,1,2,\ldots\}$ 

and  $E[X_n] = \mu$  for all  $n \ge 1$ .

Then,

$$E[X_1 + \cdots + X_Z] = \mu E[Z].$$

#### Proof:

$$E[X_1 + \cdots + X_Z | Z = k] = \mu k.$$

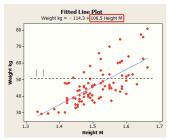
Thus, 
$$E[X_1 + \cdots + X_Z | Z] = \mu Z$$
.

Hence, 
$$E[X_1 + \cdots + X_Z] = E[\mu Z] = \mu E[Z]$$
.

# Linear Regression: Motivation

Example 1: 100 people.

Let  $(X_n, Y_n)$  = (height, weight) of person n, for n = 1, ..., 100:



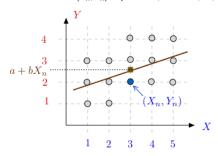
The blue line is Y = -114.3 + 106.5X. (X in meters, Y in kg.)

Best linear fit: Linear Regression.

### Motivation

Example 2: 15 people.

We look at two attributes:  $(X_n, Y_n)$  of person n, for n = 1, ..., 15:



The line Y = a + bX is the linear regression.

### **LLSE**

#### Theorer

Consider two RVs X, Y with a given distribution Pr[X = x, Y = y].

Proof 1: 
$$L[Y|X] = \hat{Y} = E[Y] + \frac{cov(X,Y)}{var(X)}(X - E[X]).$$

$$Y - \hat{Y} = (Y - E[Y]) - \frac{cov(X,Y)}{var(Y)}(X - E[X]). \quad E[Y - \hat{Y}] = 0 \text{ by linearity.}$$

Also,  $E[(Y - \hat{Y})X] = 0$ , after a bit of algebra. (See next slide.)

Combine brown inequalities:  $E[(Y - \hat{Y})(c + dX)] = 0$  for any c, d. Since:  $\hat{Y} = \alpha + \beta X$  for some  $\alpha, \beta$ , so  $\exists c, d$  s.t.  $\hat{Y} - a - bX = c + dX$ . Then,  $E[(Y - \hat{Y})(\hat{Y} - a - bX)] = 0$ .  $\forall a, b$ . Now,

$$E[(Y - a - bX)^{2}] = E[(Y - \hat{Y} + \hat{Y} - a - bX)^{2}]$$

$$= E[(Y - \hat{Y})^{2}] + E[(\hat{Y} - a - bX)^{2}] + 0 \ge E[(Y - \hat{Y})^{2}].$$

This shows that  $E[(Y-\hat{Y})^2] \le E[(Y-a-bX)^2]$ , for all (a,b). Thus  $\hat{Y}$  is the LLSE.

### LLSE

LLSE[Y|X] - best guess for Y given X.

Theorem

Consider two RVs X, Y with a given distribution Pr[X = x, Y = y]. Then,

Proof 1:  

$$L[Y|X] = \hat{Y} = E[Y] + \frac{cov(X,Y)}{var(X)}(X - E[X]).$$

$$Y - \hat{Y} = (Y - E[Y]) - \frac{cov(X,Y)}{var(X)}(X - E[X]). \quad E[Y - \hat{Y}] = 0 \text{ by linearity.}$$

Also,  $E[(Y - \hat{Y})X] = 0$ , after a bit of algebra. (next slide)

Combine brown inequalities:  $E[(Y - \hat{Y})(c + dX)] = 0$  for any c, d. Since:  $\hat{Y} = \alpha + \beta X$  for some  $\alpha, \beta$ , so  $\exists c, d$  s.t.  $\hat{Y} - a - bX = c + dX$ . Then,  $E[(Y - \hat{Y})(\hat{Y} - a - bX)] = 0, \forall a, b$ . Now,

$$E[(Y - a - bX)^{2}] = E[(Y - \hat{Y} + \hat{Y} - a - bX)^{2}]$$

$$= E[(Y - \hat{Y})^{2}] + E[(\hat{Y} - a - bX)^{2}] + 0 \ge E[(Y - \hat{Y})^{2}].$$

This shows that  $E[(Y-\hat{Y})^2] \le E[(Y-a-bX)^2]$ , for all (a,b). Thus  $\hat{Y}$  is the LLSE.

## A Bit of Algebra

$$Y - \hat{Y} = (Y - E[Y]) - \frac{cov(X,Y)}{var(X)}(X - E[X]).$$

Hence,  $E[Y - \hat{Y}] = 0$ . We want to show that  $E[(Y - \hat{Y})X] = 0$ .

Note that

$$E[(Y - \hat{Y})X] = E[(Y - \hat{Y})(X - E[X])],$$

because  $E[(Y - \hat{Y})E[X]] = 0$ .

Now,

П

$$\begin{split} & E[(Y - \hat{Y})(X - E[X])] \\ & = E[(Y - E[Y])(X - E[X])] - \frac{cov(X, Y)}{var[X]} E[(X - E[X])(X - E[X])] \\ & =^{(*)} cov(X, Y) - \frac{cov(X, Y)}{var[X]} var[X] = 0. \quad \Box \end{split}$$

(\*) Recall that cov(X, Y) = E[(X - E[X])(Y - E[Y])] and  $var[X] = E[(X - E[X])^2]$ .

## A Bit of Algebra

$$Y - \hat{Y} = (Y - E[Y]) - \frac{cov(X,Y)}{var[X]}(X - E[X]).$$

Hence,  $E[Y - \hat{Y}] = 0$ . We want to show that  $E[(Y - \hat{Y})X] = 0$ .

Note that

$$E[(Y - \hat{Y})X] = E[(Y - \hat{Y})(X - E[X])],$$

because  $E[(Y - \hat{Y})E[X]] = 0$ .

Now,

$$\begin{split} &E[(Y - \hat{Y})(X - E[X])] \\ &= E[(Y - E[Y])(X - E[X])] - \frac{cov(X, Y)}{var[X]} E[(X - E[X])(X - E[X])] \\ &= (*) cov(X, Y) - \frac{cov(X, Y)}{var[X]} var[X] = 0. \quad \Box \end{split}$$

(\*) Recall that cov(X, Y) = E[(X - E[X])(Y - E[Y])] and  $var[X] = E[(X - E[X])^2]$ .

### **Estimation Error**

We saw that the LLSE of Y given X is

$$L[Y|X] = \hat{Y} = E[Y] + \frac{cov(X,Y)}{var(X)}(X - E[X]).$$

How good is this estimator?

Or what is the mean squared estimation error?

We find

$$\begin{split} E[|Y - L[Y|X]|^2] &= E[(Y - E[Y] - (cov(X, Y)/var(X))(X - E[X]))^2] \\ &= E[(Y - E[Y])^2] - 2\frac{cov(X, Y)}{var(X)} E[(Y - E[Y])(X - E[X])] \\ &+ (\frac{cov(X, Y)}{var(X)})^2 E[(X - E[X])^2] \\ &= var(Y) - \frac{cov(X, Y)^2}{var(X)}. \end{split}$$

Without observations, the estimate is E[Y]. The error is var(Y). Observing X reduces the error.

### Estimation Error: A Picture

We saw that

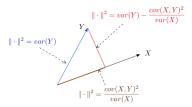
$$L[Y|X] = \hat{Y} = E[Y] + \frac{cov(X,Y)}{var(X)}(X - E[X])$$

and

$$E[|Y - L[Y|X]|^2] = var(Y) - \frac{cov(X, Y)^2}{var(X)}.$$

Here is a picture when E[X] = 0, E[Y] = 0:

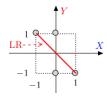
Dimensions correspond to sample points, uniform sample space.



Vector *Y* at dimension  $\omega$  is  $\frac{1}{\sqrt{\Omega}}Y(\omega)$ 

# Linear Regression Examples

### Example 3:

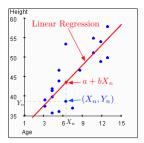


We find:

$$\begin{split} E[X] &= 0; E[Y] = 0; E[X^2] = 1/2; E[XY] = -1/2; \\ var[X] &= E[X^2] - E[X]^2 = 1/2; cov(X,Y) = E[XY] - E[X]E[Y] = -1/2; \\ LR: \hat{Y} &= E[Y] + \frac{cov(X,Y)}{var[X]}(X - E[X]) = -X. \end{split}$$

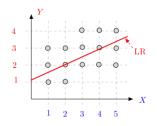
## **Linear Regression Examples**

### Example 1:



# Linear Regression Examples

Example 4:



We find:

$$\begin{split} E[X] &= 3; E[Y] = 2.5; E[X^2] = (3/15)(1+2^2+3^2+4^2+5^2) = 11; \\ E[XY] &= (1/15)(1\times1+1\times2+\dots+5\times4) = 8.4; \\ var[X] &= 11-9 = 2; cov(X,Y) = 8.4-3\times2.5 = 0.9; \\ \text{LR: } \hat{Y} &= 2.5 + \frac{0.9}{2}(X-3) = 1.15 + 0.45X. \end{split}$$

## **Linear Regression Examples**

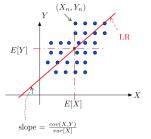
#### Example 2:



We find:

$$\begin{split} E[X] &= 0; E[Y] = 0; E[X^2] = 1/2; E[XY] = 1/2; \\ var[X] &= E[X^2] - E[X]^2 = 1/2; cov(X,Y) = E[XY] - E[X]E[Y] = 1/2; \\ \text{LR: } \hat{Y} &= E[Y] + \frac{cov(X,Y)}{var[X]}(X - E[X]) = X. \end{split}$$

# LR: Another Figure



Note that

- ▶ the LR line goes through (E[X], E[Y])
- ▶ its slope is  $\frac{cov(X,Y)}{var(X)}$ .

# **Quadratic Regression**

Let X, Y be two random variables defined on the same probability space.

**Definition:** The quadratic regression of Y over X is the random variable

$$Q[Y|X] = a + bX + cX^2$$

where a, b, c are chosen to minimize  $E[(Y - a - bX - cX^2)^2]$ .

**Derivation:** We set to zero the derivatives w.r.t. a, b, c. We get

$$0 = E[Y - a - bX - cX^2] = E[Y] - a - bE[X] - cE[X^2]$$

$$0 = E[(Y - a - bX - cX^{2})X] = E[XY] - a - bE[X^{2}] - cE[X^{3}]$$

$$0 = E[(Y - a - bX - cX^2)X^2] = E[X^2Y] - aE[X^2] - bE[X^3] - cE[X^4]$$

We solve these three equations in the three unknowns (a, b, c).

# Summary

### Linear Regression

Mean Squared: E[Y] is best mean squared estimator for Y. MMSE: E[Y|X] is best mean squared estimator for Y given X. Linear Regression:  $L[Y|X] = E[Y] + \frac{cov(X,Y)}{var(X)}(X - E[X])$ 

Can do other forms of functions as well, e.g., quadratic.

Warning: assumes you know distribution. Sample Points "are" distribution in this class. Statistics: Fix the assumption above.