

## Lecture 16: Continuing Probability.

Events, Conditional Probability, Independence, Bayes' Rule

# Probability Basics:Poll

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- (A) A set and a function on the elements.
- (B) The values of the function are real numbers.
- (C) The values of the function are positive integers.
- (D) An element of the set is an outcome.
- (E) There is an experiment associated with a probability space.
- (F) The values in the set are integers.

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- (A),(B), (D), (E).

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    1.  $0 \leq Pr[\omega] \leq 1$ .
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  - ▶ **Events.**  
Event  $A \subseteq \Omega$ ,  $Pr[A] = \sum_{\omega \in A} Pr[\omega]$ .

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A, B, C, D

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 $= \sum_{\omega \in A} Pr[\omega] + \sum_{\omega \in B} Pr[\omega]$  since  $A \cap B = \emptyset$ .  $= Pr[A] + Pr[B]$

(b) Either induction, or argue over sample points.

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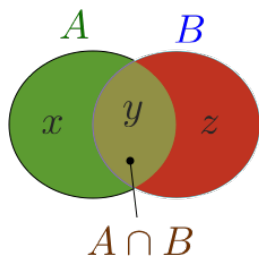
Proofs for (a) and (c)? Next...

## Inclusion/Exclusion

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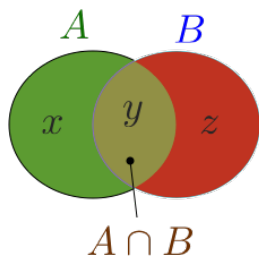
$$Pr[B] = y + z$$

$$Pr[A \cap B] = y$$

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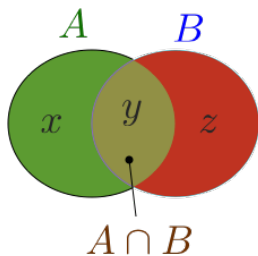
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Another view.

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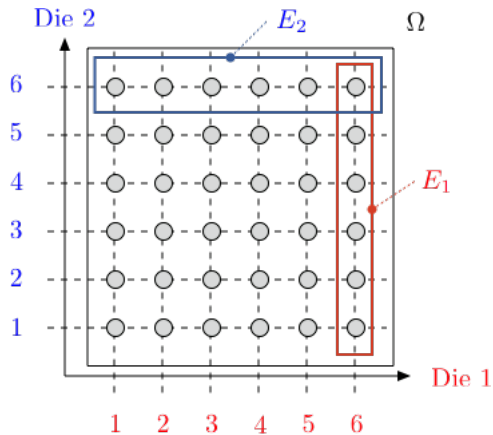
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Another view. Any  $\omega \in A \cup B$  is in  $A \cap \bar{B}$ ,  $A \cup B$ , or  $\bar{A} \cap B$ . So, add it up.



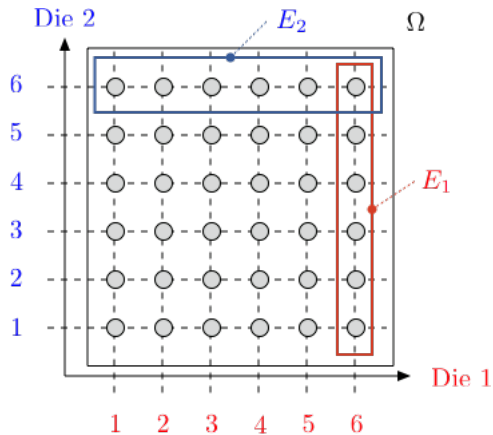
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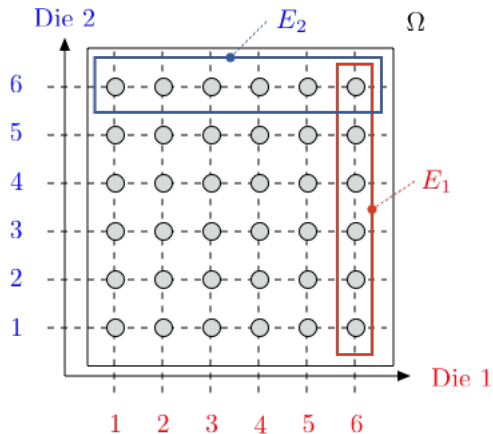
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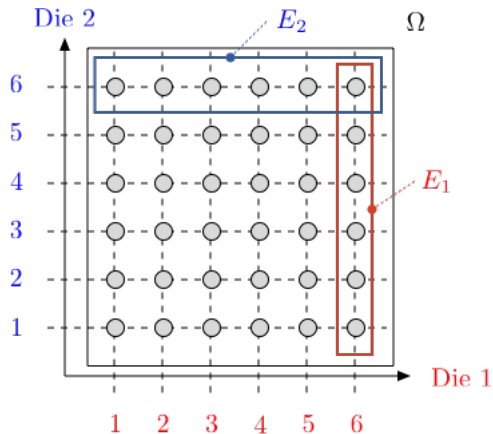
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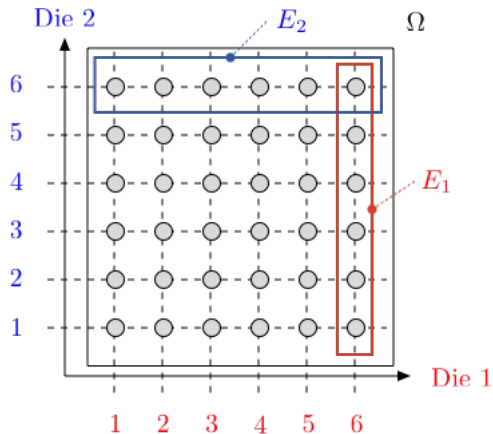


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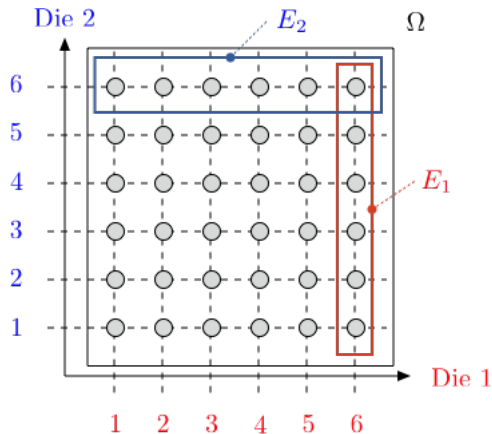
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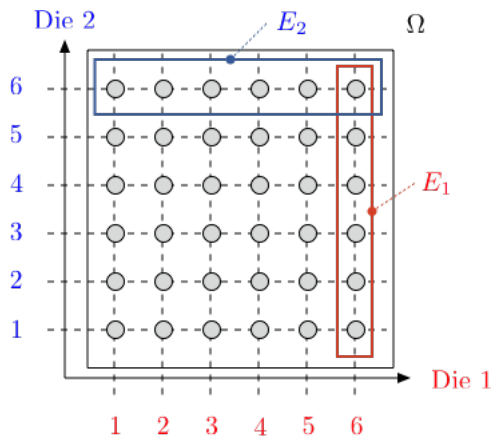
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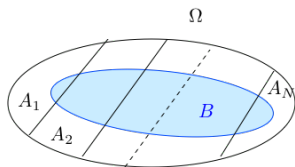
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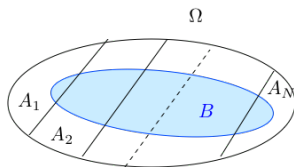
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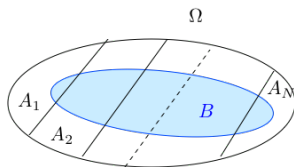


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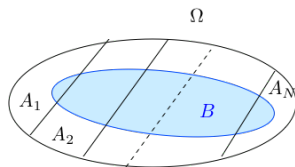
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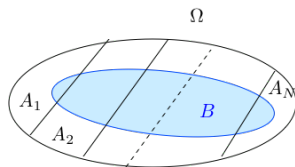
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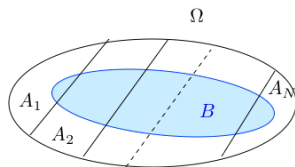
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Adding up probability of them, get  $Pr[\omega]$  in sum.

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Indeed,  $B$  is the union of the disjoint sets  $A_n \cap B$  for  $n = 1, \dots, N$ .

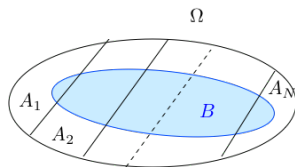
In “math”:  $\omega \in B$  is in exactly one of  $A_i \cap B$ .

Adding up probability of them, get  $Pr[\omega]$  in sum.

..Did I say...

# Total probability

Assume that  $\Omega$  is the union of the disjoint sets  $A_1, \dots, A_N$ .



Then,

$$Pr[B] = Pr[A_1 \cap B] + \dots + Pr[A_N \cap B].$$

Indeed,  $B$  is the union of the disjoint sets  $A_n \cap B$  for  $n = 1, \dots, N$ .

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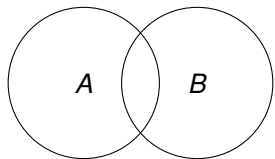
..Did I say...

Add it up.

# Conditional Probability.

**Definition:** The **conditional probability** of  $B$  given  $A$  is

$$Pr[B|A] = \frac{Pr[A \cap B]}{Pr[A]}$$

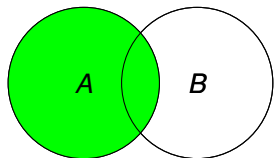




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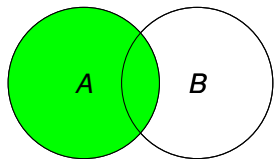


In  $A!$

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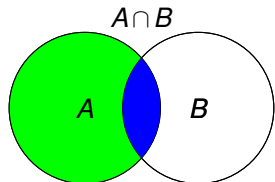


In  $A$ !  
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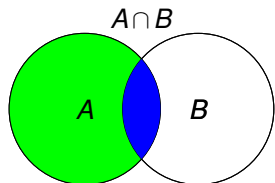


In  $A$ !  
In  $B$ ?  
Must be in  $A \cap B$ .

# Conditional Probability.

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In  $A$ !

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Must be in  $A \cap B$ .

$$Pr[B|A] = \frac{Pr[A \cap B]}{Pr[A]}.$$

## Conditional probability: example.

Two coin flips.

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Two coin flips. First flip is heads.

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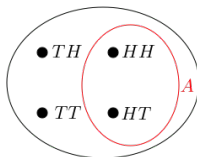
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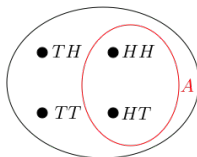
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New sample space:  $A$ ;

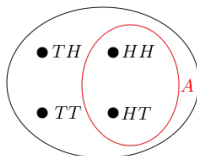
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New sample space:  $A$ ; uniform still.

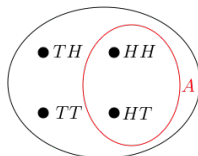
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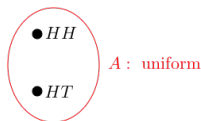
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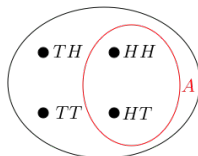
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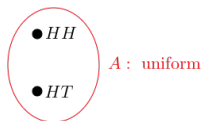
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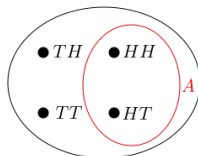
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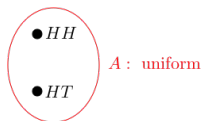
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The probability of two heads if the first flip is heads.

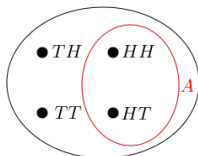
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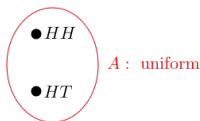
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**The probability of  $B$  given  $A$**

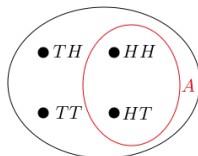
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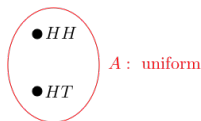
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The probability of two heads if the first flip is heads.

**The probability of  $B$  given  $A$  is  $1/2$ .**

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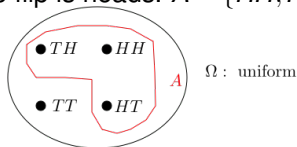
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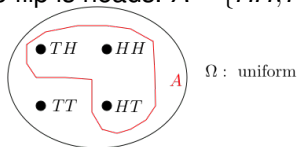
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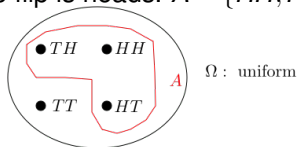
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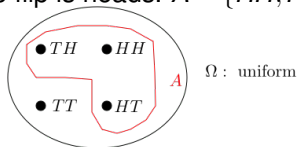
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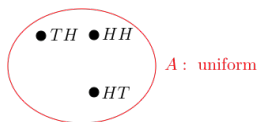
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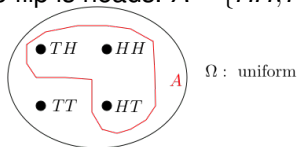
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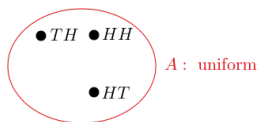
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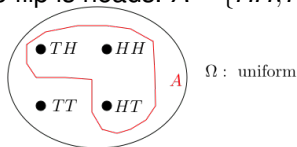
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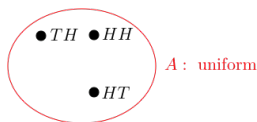
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New sample space:  $A$ ; uniform still.



Event  $B =$  two heads.

The probability of two heads if at least one flip is heads.



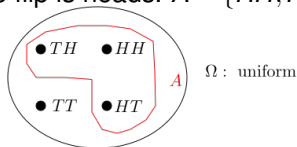
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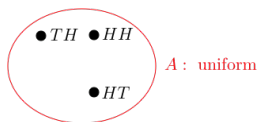
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The probability of two heads if at least one flip is heads.

**The probability of  $B$  given  $A$**

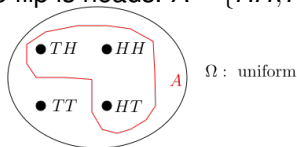
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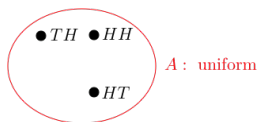
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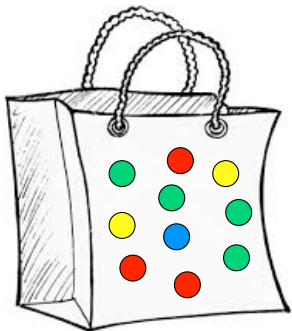
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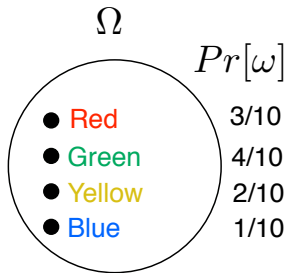
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## Conditional Probability: A non-uniform example

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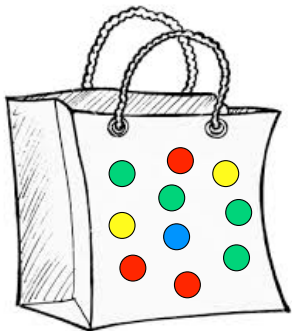


Physical experiment

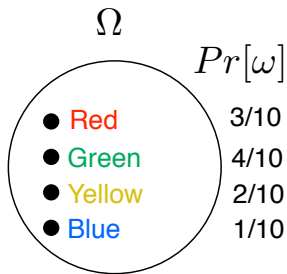


Probability model

# Conditional Probability: A non-uniform example



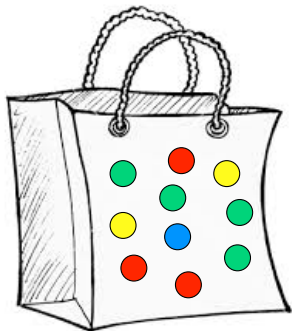
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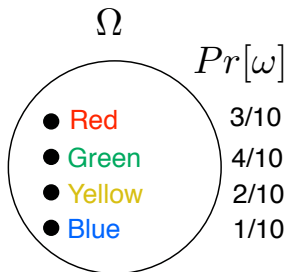
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$$\Omega = \{\text{Red, Green, Yellow, Blue}\}$$

# Conditional Probability: A non-uniform example



Physical experiment

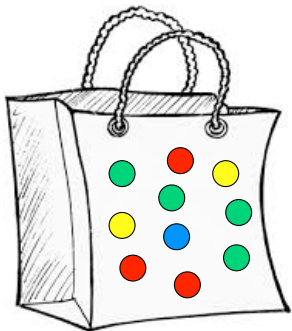


Probability model

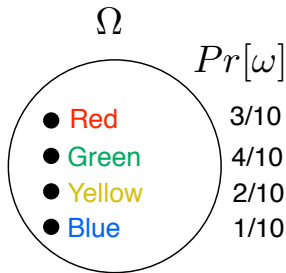
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$$Pr[\text{Red} | \text{Red or Green}] =$$

# Conditional Probability: A non-uniform example



Physical experiment

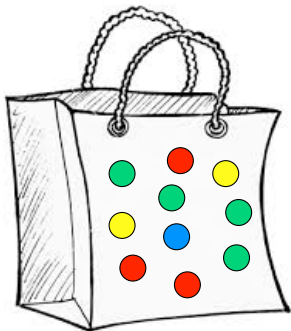


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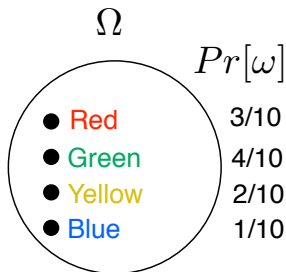
$$\Omega = \{\text{Red, Green, Yellow, Blue}\}$$

$$Pr[\text{Red} | \text{Red or Green}] = \frac{3}{7} =$$

# Conditional Probability: A non-uniform example



Physical experiment



Probability model

$$\Omega = \{\text{Red, Green, Yellow, Blue}\}$$
$$Pr[\text{Red} | \text{Red or Green}] = \frac{3}{7} = \frac{Pr[\text{Red} \cap (\text{Red or Green})]}{Pr[\text{Red or Green}]}$$



## Another non-uniform example

Consider  $\Omega = \{1, 2, \dots, N\}$  with  $Pr[n] = p_n$ .

## Another non-uniform example

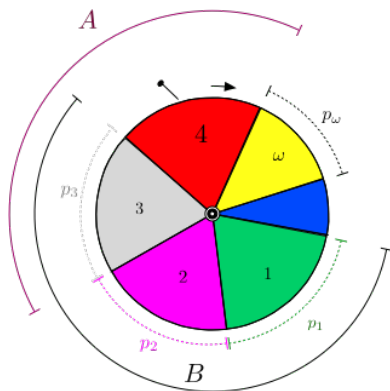
Consider  $\Omega = \{1, 2, \dots, N\}$  with  $Pr[n] = p_n$ .

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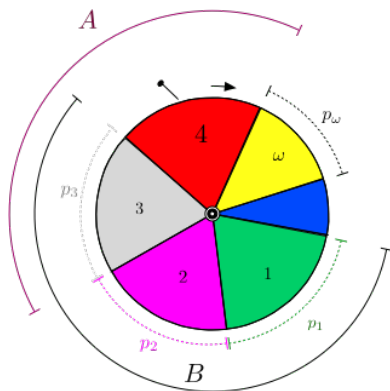
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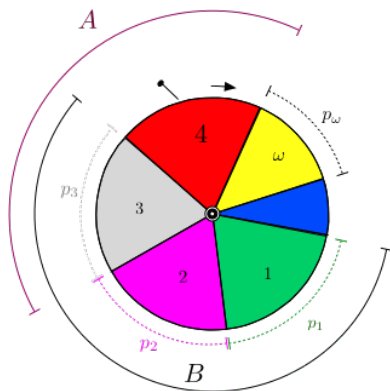


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$$Pr[A|B] = \frac{p_3}{p_1 + p_2 + p_3} = \frac{Pr[A \cap B]}{Pr[B]}.$$

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Consider  $\Omega = \{1, 2, \dots, N\}$  with  $Pr[n] = p_n$ .

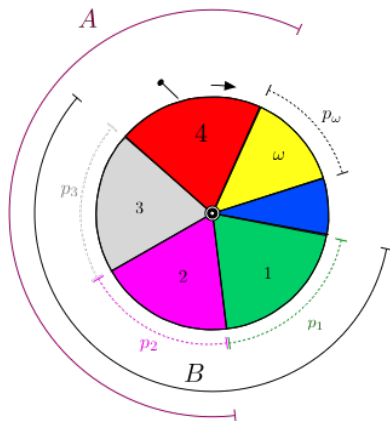
## Yet another non-uniform example

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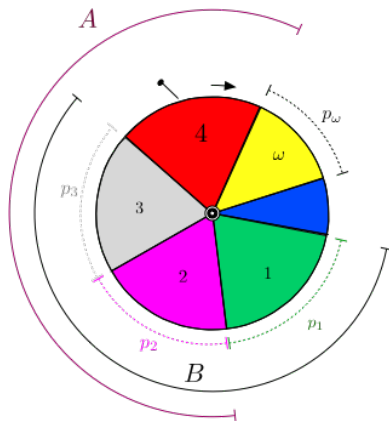




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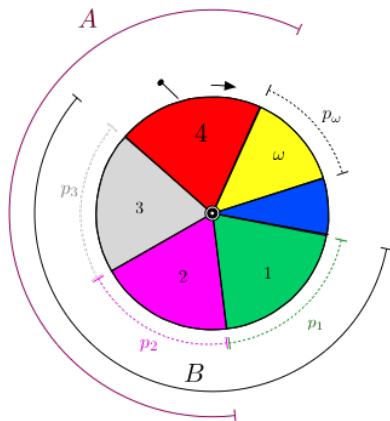


$$Pr[A|B] =$$

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$$Pr[A|B] = \frac{p_2 + p_3}{p_1 + p_2 + p_3} = \frac{Pr[A \cap B]}{Pr[B]}.$$

## More fun with conditional probability.

Toss a red and a blue die, sum is 4,

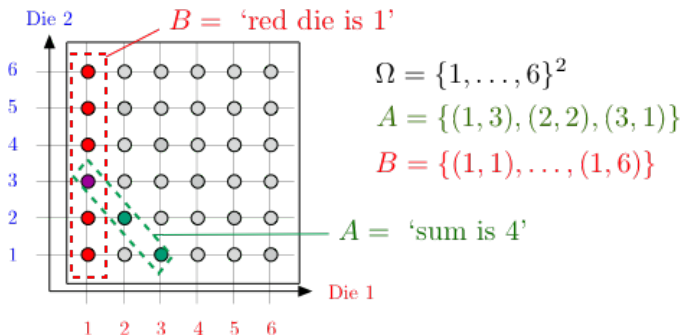
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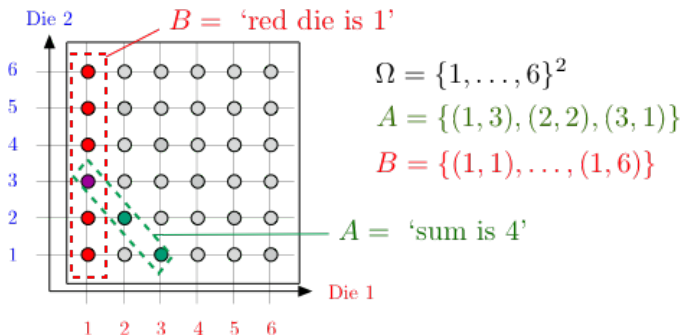
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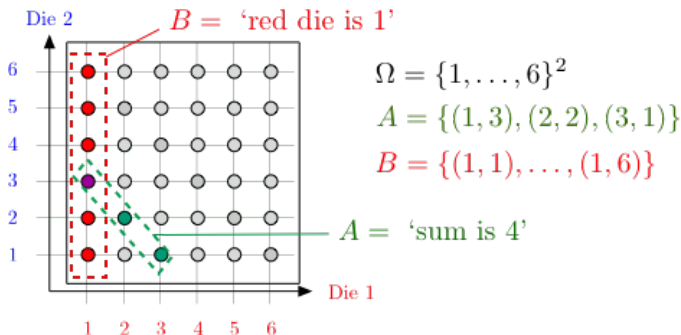


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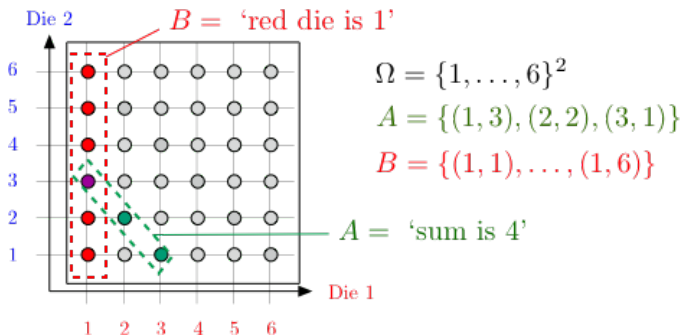


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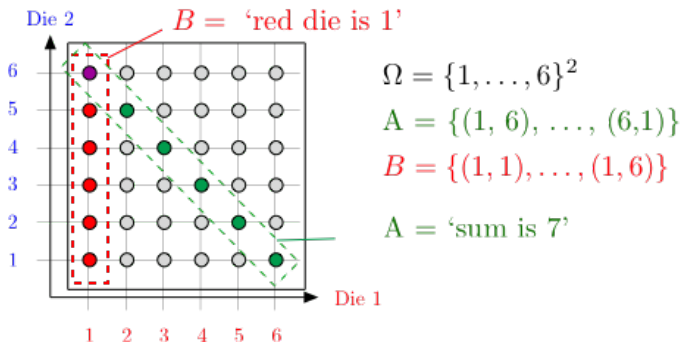
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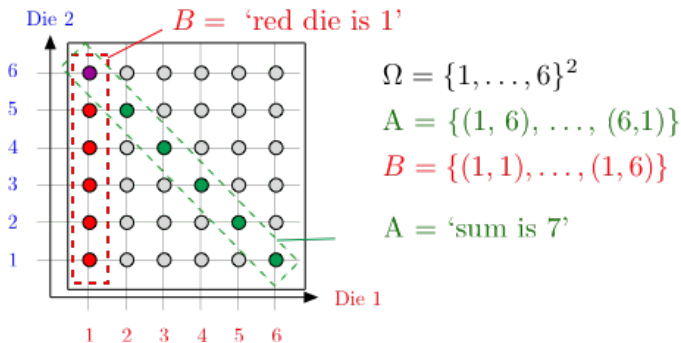
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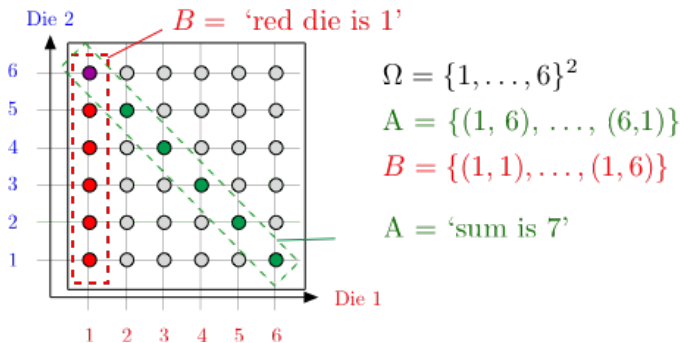


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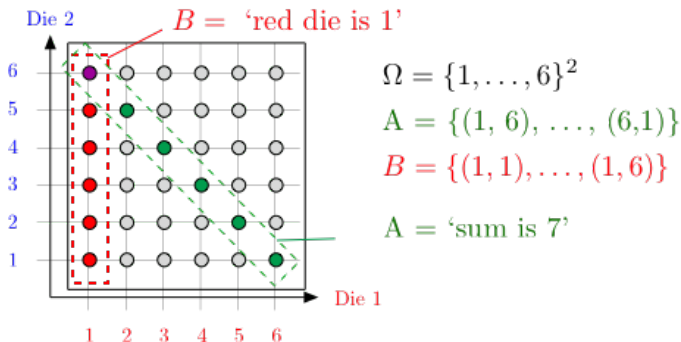


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Observing  $A$  does not change your mind about the likelihood of  $B$ .

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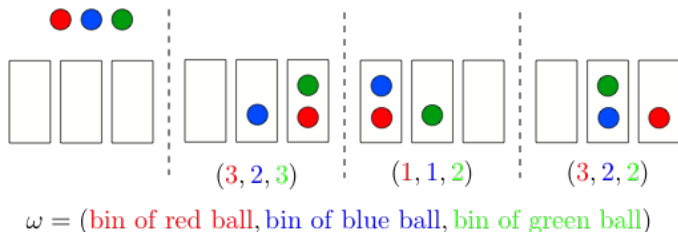
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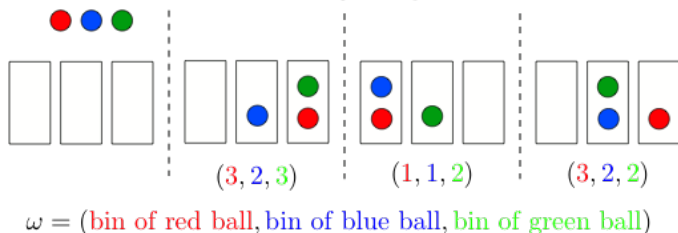


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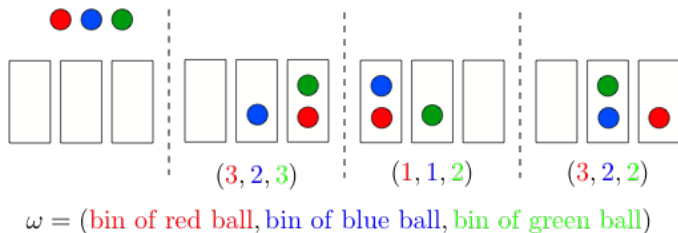


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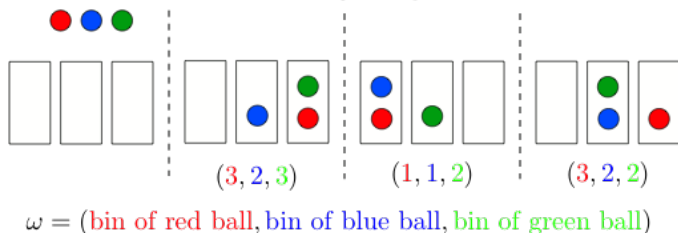
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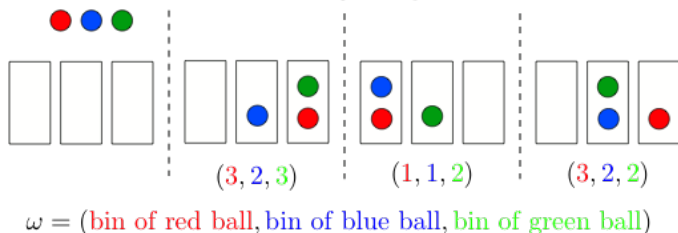
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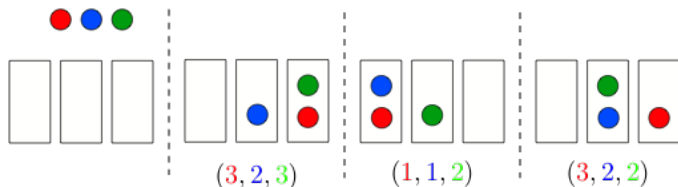
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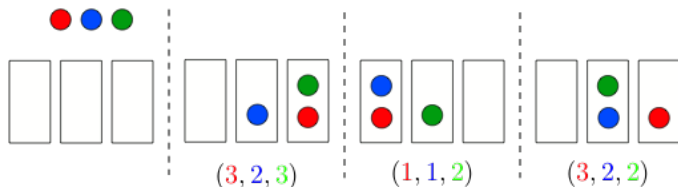
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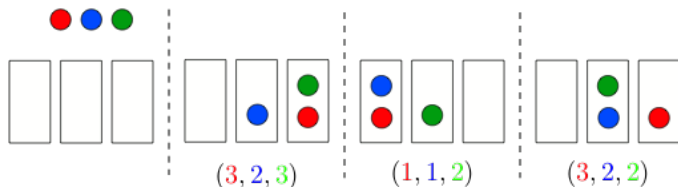
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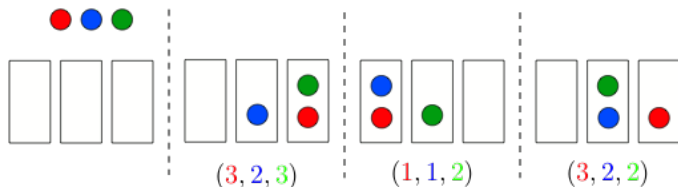
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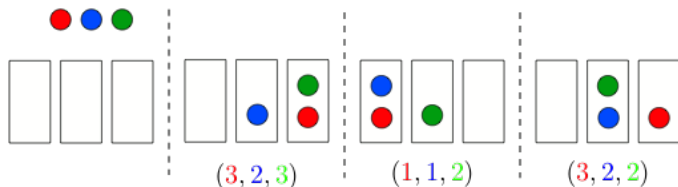
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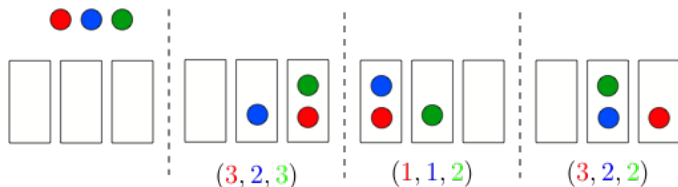
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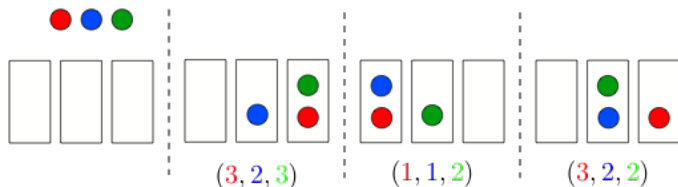


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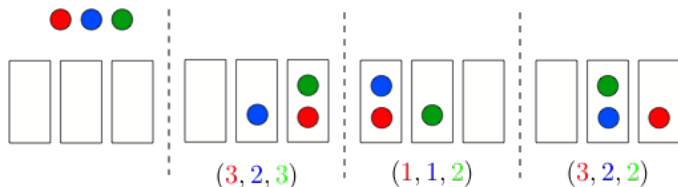
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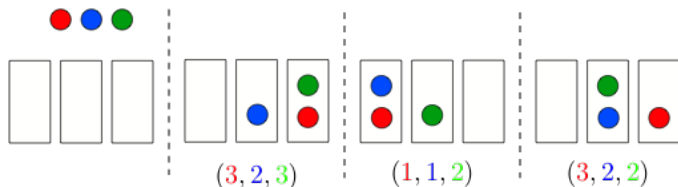
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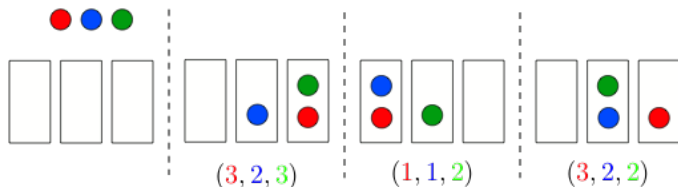
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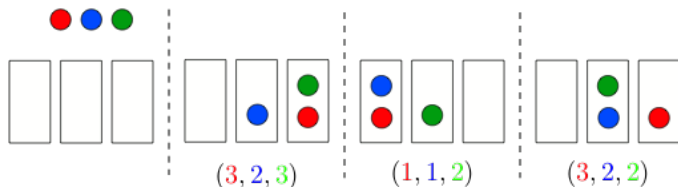
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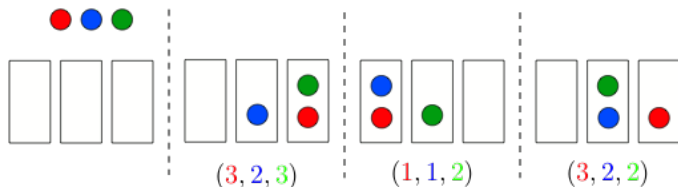
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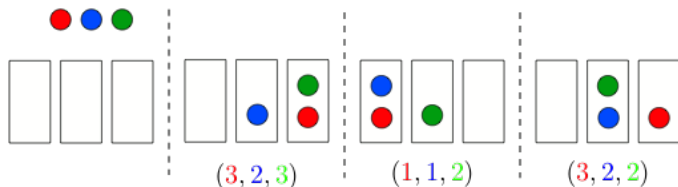
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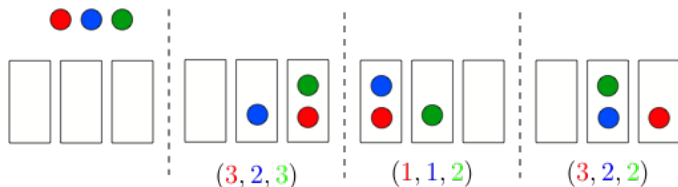
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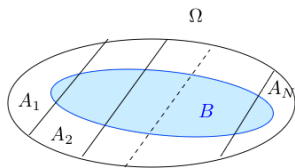
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More about such questions later. For fun, check “N. Taleb: Fooled by randomness.”

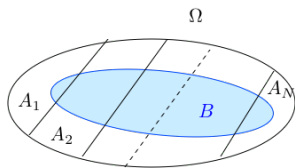
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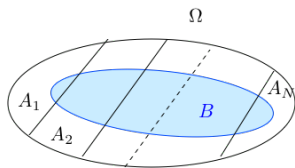


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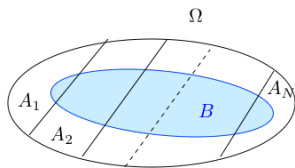
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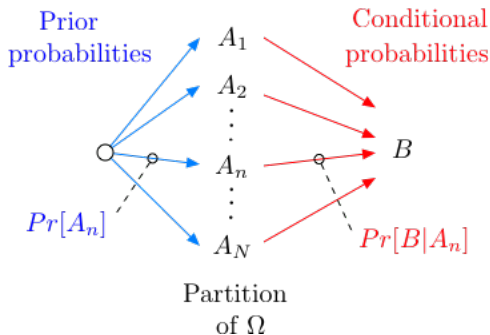
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Thus,

$$Pr[A|B] = \frac{Pr[A]Pr[B|A]}{Pr[B]} = \frac{(1/2)(1/2)}{(1/2)(1/2) + (1/2)0.6} \approx 0.45.$$

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- (B) Roll two dice,  $A =$  sum is 3 and  $B =$  red die is 1.
- (C) Flip two coins,  $A =$  coin 1 is heads and  $B =$  coin 2 is tails.
- (D) Throw 3 balls into 3 bins,  $A =$  bin 1 is empty and  $B =$  bin 2 is empty

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  - (B) Roll two dice,  $A =$  sum is 3 and  $B =$  red die is 1.
  - (C) Flip two coins,  $A =$  coin 1 is heads and  $B =$  coin 2 is tails.
  - (D) Throw 3 balls into 3 bins,  $A =$  bin 1 is empty and  $B =$  bin 2 is empty
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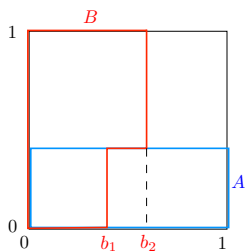
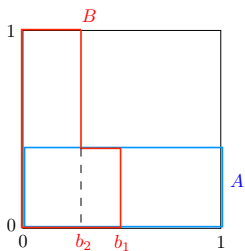
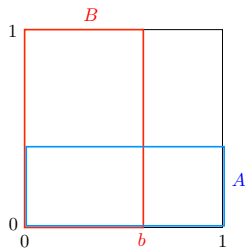
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## Conditional Probability: Pictures

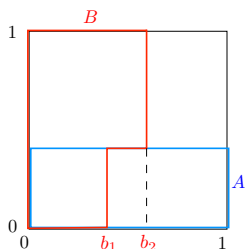
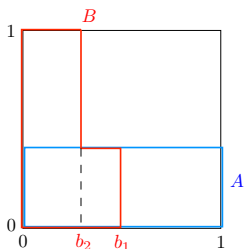
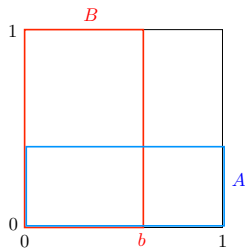
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Illustrations: Pick a point uniformly in the unit square



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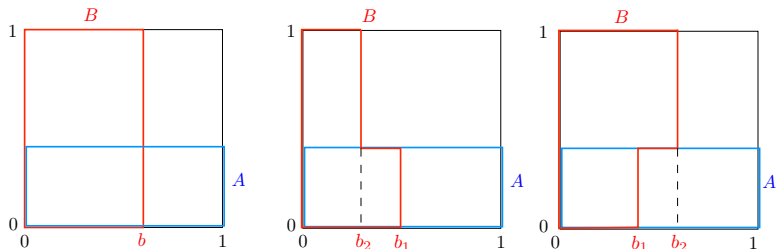
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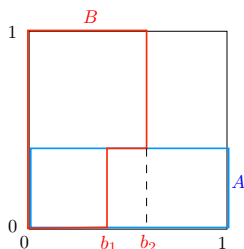
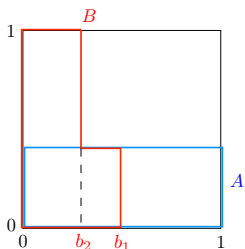
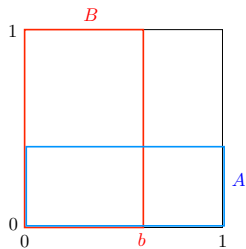
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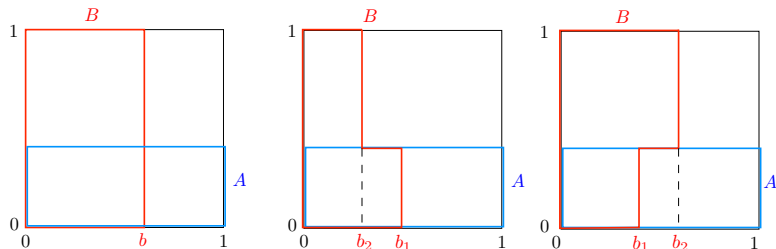
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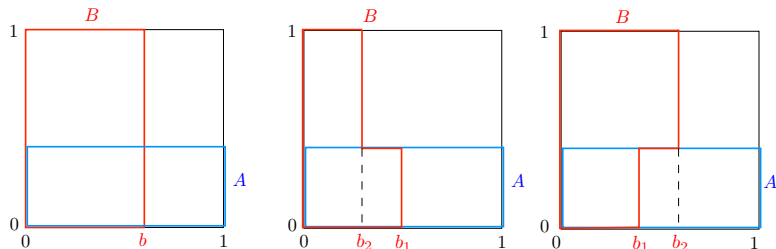
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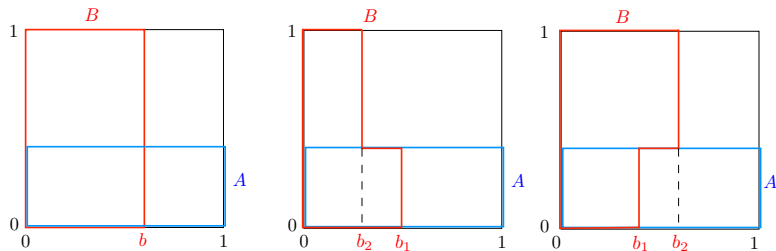
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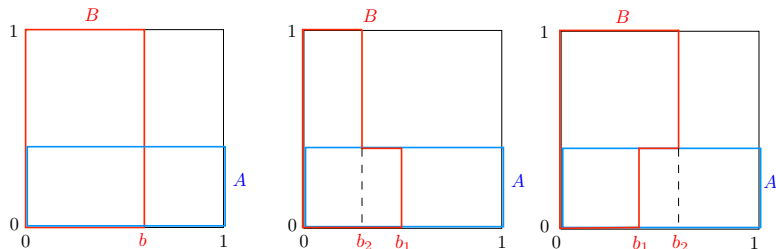


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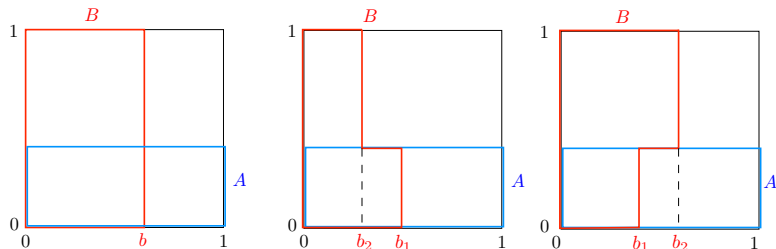
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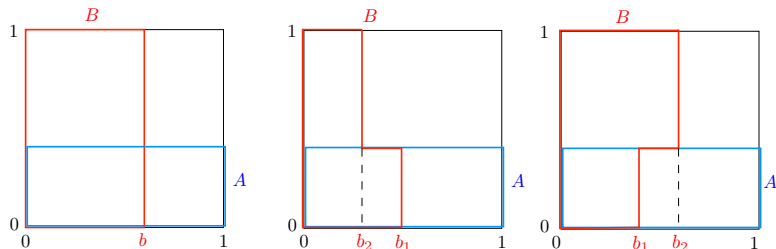
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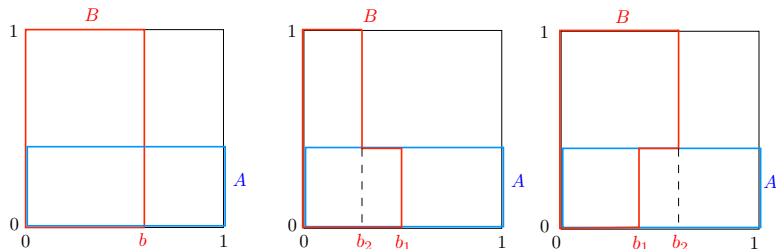
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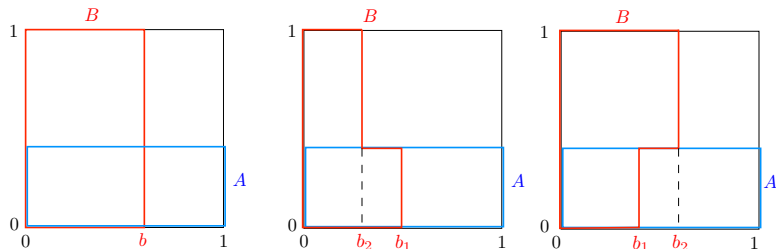
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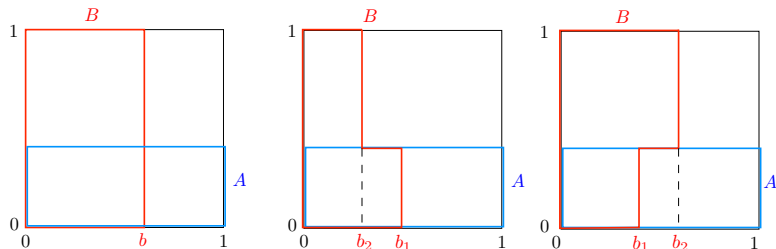
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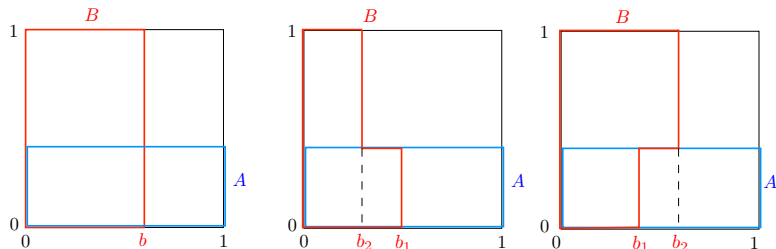
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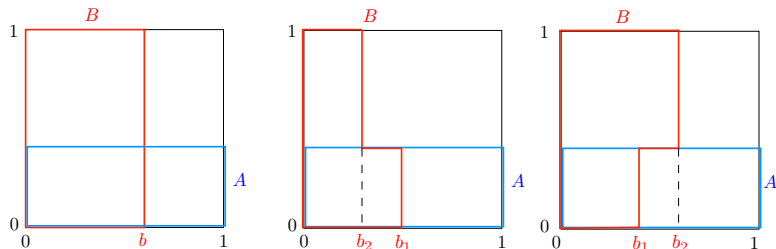
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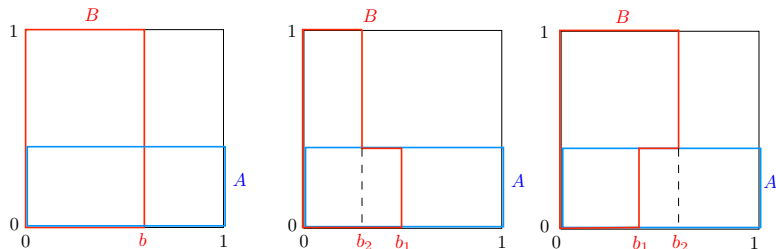


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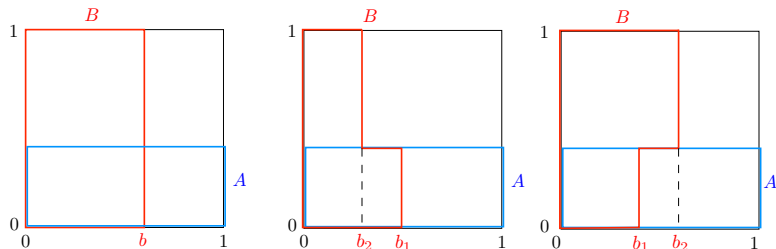
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- ▶ Left:  $A$  and  $B$  are independent.  $Pr[B] = b$ ;  $Pr[B|A] = b$ .
- ▶ Middle:  $A$  and  $B$  are positively correlated.  
 $Pr[B|A] = b_1 > Pr[B|\bar{A}] = b_2$ . Note:  $Pr[B] \in (b_2, b_1)$ .
- ▶ Right:  $A$  and  $B$  are negatively correlated.  
 $Pr[B|A] = b_1 < Pr[B|\bar{A}] = b_2$ .

# Conditional Probability: Pictures

Illustrations: Pick a point uniformly in the unit square



- ▶ Left:  $A$  and  $B$  are independent.  $Pr[B] = b$ ;  $Pr[B|A] = b$ .
- ▶ Middle:  $A$  and  $B$  are positively correlated.  
 $Pr[B|A] = b_1 > Pr[B|\bar{A}] = b_2$ . Note:  $Pr[B] \in (b_2, b_1)$ .
- ▶ Right:  $A$  and  $B$  are negatively correlated.  
 $Pr[B|A] = b_1 < Pr[B|\bar{A}] = b_2$ . Note:  $Pr[B] \in (b_1, b_2)$ .